

Lecture 37

37-1

• Polar coordinates: $x = r \cos \theta$, $y = r \sin \theta$

$$dA = r dr d\theta$$

• A lamina, D , with density function $\rho(x, y)$:

i) mass = $m = \iint_D \rho dA$

ii) moment about x -axis = $M_x = \iint_D y \rho dA$

iii) moment about y -axis = $M_y = \iint_D x \rho dA$.

iv) center of mass = (\bar{x}, \bar{y}) where $\bar{x} = \frac{M_y}{m}$, $\bar{y} = \frac{M_x}{m}$

• A solid, E , with density function $\rho(x, y, z)$:

i) mass = $m = \iiint_E \rho dV$

ii) moment about yz -plane = $M_{yz} = \iiint_E x \rho dV$

• xz -plane = $M_{xz} = \iiint_E y \rho dV$

• xy -plane = $M_{xy} = \iiint_E z \rho dV$

iii) center of mass = $(\bar{x}, \bar{y}, \bar{z})$

$$\bar{x} = \frac{M_{yz}}{m}, \quad \bar{y} = \frac{M_{xz}}{m}, \quad \bar{z} = \frac{M_{xy}}{m}.$$

• Be able to read the region of integration from the bounds of a triple integral (usually in order to change the order of integration).

e.g.: $\int_0^1 \int_x^{2x} \int_0^y 2xyz dz dy dx$ is an integral over

the region bounded by the planes:

$z=0, z=y, y=x, y=2x, x=0, \text{ and } x=1.$

• Cylindrical coordinates: $x=r\cos\theta, y=r\sin\theta, \text{ ~~z=z~~ } z=z$
 $dV = r dr d\theta dz$

• Spherical coordinates: $x=\rho\cos\theta\sin\phi, y=\rho\sin\theta\sin\phi, z=\rho\cos\phi$
 $dV = \rho^2 \sin\phi d\rho d\theta d\phi$

• General Change of Variables

- Used to either simplify the region or the integral

- For a transformation $T(u,v) = (x(u,v), y(u,v))$ (i.e. $x = x(u,v), y = y(u,v)$) which sends a region S in the uv -plane to a region R in the xy -plane (i.e. $T(S) = R$),

$$\iint_R f(x,y) dA = \iint_S f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

• You can use the fact that $\frac{\partial(x,y)}{\partial(u,v)} = \frac{1}{\left(\frac{\partial(u,v)}{\partial(x,y)}\right)}$ if when you choose u & v , x & y are hard to solve for.

• If C is parametrized by $\vec{r}(t)$, $a \leq t \leq b$

i) $\int_C f ds = \int_a^b f(\vec{r}(t)) |\vec{r}'(t)| dt$

ii) $\vec{r}(t) = \langle x(t), y(t) \rangle$

$\int_C P dx + Q dy = \int_0^{2\pi} (P(\vec{r}(t)) x'(t) + Q(\vec{r}(t)) y'(t)) dt$
 $= \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt = \int_C \vec{F} \cdot d\vec{r}$, $\vec{F}(x,y) = \langle P(x,y), Q(x,y) \rangle$

iii) $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$, $a \leq t \leq b$, $\vec{F}(x,y,z) = \langle P, Q, R \rangle$

$\int_C P dx + Q dy + R dz = \int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$
 $= \int_a^b (P(\vec{r}(t)) x'(t) + Q(\vec{r}(t)) y'(t) + R(\vec{r}(t)) z'(t)) dt$

• $\int_{-C} \vec{F} \cdot d\vec{r} = - \int_C \vec{F} \cdot d\vec{r}$

• $\int_C \nabla f \cdot d\vec{r} = f(B) - f(A)$: Fundamental Theorem of Line Integrals

C is a path starting at A and ending at B .

• A vector field, ~~\vec{F}~~ \vec{F} , is conservative if

$$\vec{F} = \nabla f$$

for some scalar function f . f is called a potential function for \vec{F} .

• To try to find a potential, f , for $\vec{F} = \langle P, Q \rangle$, we assume $\vec{F} = \nabla f = \langle f_x, f_y \rangle$, use $P = f_x$ & $Q = f_y$, and integrate to try to find f .

Compare with the equation you didn't integrate to solve for the arbitrary function obtained from the integration.

• Green's Theorem

$$\oint_C P dx + Q dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

where $C = \partial D$.